# **MTi-670G**

- Rugged, IP68-rated GNSS/INS
- 0.2 deg roll/pitch & sub-meter level position accuracy
- u-blox ZED F9 GNSS receiver

The MTi-670G is a GNSS/INS with a rugged housing featuring IP68 protection against environmental influences. Building on the proven MTi 600-series technology it enables a robust and easy to use m-level positioning and orientation tracking. If features an incredibly powerful onboard u-blox ZED F9 GNSS receiver to provide superior positioning performance. It is designed for seamless integration and interfacing with other equipment.

The MTi-670G is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms including ROS.



Roll, Pitch	0,2 deg RMS
Yaw/Heading	0.8 deg RMS
Position	<1m CEP
Velocity	0.05m/c PMS

# **Gyroscope**

Standard full range	2000 deg/s
In-run bias stability	4 deg/h
Bandwidth (-3dB)	500 Hz
Noise Density	0.004 $^{\rm o}/{\rm s}/\sqrt{\rm Hz}$
g-sensitivity (calibr.)	0.001 °/s/g

## **Accelerometer**

Standard full range	10 g
In-run bias stability	10 (x,y) 15(z) μg
Bandwidth (-3dB)	500 Hz
Noise Density	60 μg/√Hz

# Magnetometer

Standard full range ————	+/- 8 G
Total RMS noise	1 mG
Non-linearity	0.2%
Resolution	0.25 mG

### **GNSS Receiver**

Brand	u-blox
Model	ZED F9
RTCM input port	n/a

# **Barometer**

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Standard full range	300-1250 hPa
Total RMS noise	1.2 Pa
Relative accuracy	+/- 8 Pa (~0.5m)



- White label and OEM integration options available
- 3D models available on request
- Available online via Digi-Key, Mouser, Farnell and local distributors

# **Mechanical**

IP-rating	IP68
Operating Temperature ———	-40 to 85 °C
Casing material	Aluminum
Mounting orientation ————	No restriction, full 360° in all axes
Dimensions —————	56.5x40.9x36.75 mm
Connector	Main: ODU (AMC HD 12 pins)
	RTCM: DNC
	Antenna: SMA
Weight ————	98 g
Certifications —————	CE, FCC, RoHS
Flootvicel	

### **Electrical**

Input voltage	4.5 to 24V
Power consumption (typ)	<1 W

# Interfaces / IO

Interfaces	CAN, RS232
Sync Options	SyncIn, SyncOut, ClockSync
Protocols	Xbus, ASCII (NMEA) or CAN
Clock drift	1 ppm (or external)
Output Frequency	Up to 2kHz, 400 Hz SDI
Built-in-self test	Gyr, Acc, Mag, Baro, GNSS

## Software Suite

Software Suite	
GUI (Windows/Linux)	—— MT Manager Firmware updater,
	Magnetic Field Mapper
SDK (Example code)	C++, C#, Python, Matlab, Nucleo,
	public source code
Drivers	LabVIEW, ROS, GO
Support	BASE by XSENS: online manuals,
	community and knowledge base



