## MTi-620

- Small, IP51-rated VRU
- 0.2 deg roll/pitch accuracy

• Full Graphical User Interface (GUI) and Software Development Kit (SDK) available

The MTi-620 is a Vertical Reference System with a small form-factor design for deep integration into your application. Building on the proven MTi 600-series technology it enables a robust and easy to use orientation tracking. It is designed for easy integration and seamless interfacing with other equipment.

The MTi-620 is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms including ROS.

## 31.50 mm - 28.00 mm

- White label and OEM integration options available
- 3D models available on request
- Available online via Digi-Key, Mouser, Farnell and local distributors

| Sensor Fusion Performan     | се                      | Mechanical              |                                       |
|-----------------------------|-------------------------|-------------------------|---------------------------------------|
| Roll, Pitch                 | 0,2 deg RMS             | IP-rating               | — IP51                                |
| Yaw/Heading                 | unreferenced, low drift | Operating Temperature   | -40 to 85 °C                          |
| Strapdown Integration (SDI) | Yes                     | Casing material         | PC-ABS                                |
| Gyroscope                   |                         | Mounting orientation    | No restriction, full 360° in all axes |
| Standard full range         | 2000 deg/s              | Dimensions              | 28x31.5x13 mm                         |
| In-run bias stability       | 4 deg/h                 | Connector               | Main: Phoenix Contact 16 pin, 1.27 mm |
| Bandwidth (-3dB)            | 500 Hz                  |                         | pitch                                 |
| Noise Density               | 0.004 º/s/√Hz           | Weight                  | — 8.9 g                               |
| g-sensitivity (calibr.)     | 0.001 °/s/g             | Certifications          | CE, FCC, RoHS                         |
| Accelerometer               |                         | Electrical              |                                       |
| Standard full range         | 10 g                    | Input voltage           | 4.5 to 24V                            |
| In-run bias stability       | 10 (x,y) 15(z) μg       | Power consumption (typ) | <1 W                                  |
| Bandwidth (-3dB)            | 500 Hz                  | Interfaces / IO         |                                       |
| Noise Density               | 60 µg/√Hz               | Interfaces              | UART, CAN, RS232                      |
| Magnetometer                |                         | Sync Options            | SyncIn, SyncOut, ClockSync            |
| Standard full range         | +/- 8 G                 | Protocols               | Xbus, ASCII (NMEA) or CAN             |
| Total RMS noise             | 1 mG                    | Clock drift             | 10 ppm (or external)                  |
| Non-linearity               | 0.2%                    | Output Frequency        | Up to 2 kHz, 400 Hz SDI               |
| Resolution                  | 0.25 mG                 | Built-in-self test      | Gyr, Acc, Mag, Baro                   |
| GNSS Receiver               |                         | Software Suite          |                                       |
| Brand                       | n/a                     | GUI (Windows/Linux)     | MT Manager Firmware updater,          |
| Model                       | n/a                     |                         | Magnetic Field Mapper                 |
| RTCM input port             | n/a                     | SDK (Example code)      | C++, C#, Python, Matlab, Nucleo,      |
| Barometer                   |                         |                         | public source code                    |
| Standard full range         | 300-1250 hPa            | Drivers                 | LabVIEW, ROS, GO                      |
| Total RMS noise             | 1.2 Pa                  | Support                 | BASE by XSENS: online manuals,        |
|                             | +/- 8 Pa (~0.5m)        |                         |                                       |
| Relative accuracy           | +/- o Pa (20.511)       |                         |                                       |





Unless stated otherwise, all specifications are typical. Specifications subject to change without notice.